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Abstract

We propose a new *linear logic* completion with the aim of filling the gap between previous works relating linear logic and negation as failure [2, 4, 7] and sequent calculi used to encode the evaluation of normal programs [13, 9, 14]. More precisely, via an embedding of the SLDNF calculus of Lifschitz in Forum [12], we present a linear logic completion that provides us both a declarative (via the resulting Forum theory) and an operational (via the notion of goal-driven proofs peculiar of Forum) description of negation as failure.

Keywords. Negation as failure, sequent calculi, linear logic.

1 Introduction

The negation as finite failure rule of Clark [5] is defined as follows. Given a ground atom A, $\neg A$ succeeds if and only if A finitely fails, i.e., every SLD-derivation for A is finite and does not end with the empty clause. Symmetrically, $\neg A$ finitely fails if and only if A succeeds. The corresponding extension of SLD-resolution, namely SLDNF-resolution, has to deal with a formalization of derivation-trees much more complex with respect to the one for SLD-resolution. A precise definition of SLDNF-trees has been stated by Martelli and Tricomi [11] and Apt and Doets [1]. A different approach to the formalization of negation as failure is based on calculi à la Gentzen. Examples of sequent-calculi for SLD and SLDNF have been given by Mints [13], Sheperdson [14], and Lifschitz [9] among the others. These presentations are more intuitive than the original definition of [5, 10]. Furthermore, they simplify the proof of soundness and completeness results that can now be proved by induction on the structure of proof-trees.

In this paper we investigate the problem of finding general purpose logical systems in which to embed the above mentioned proof calculi for negations as failure. As case-study, we show that the Lifschitz's proof calculus [9] can be embedded in a proof-theoretical presentation of linear logic, namely Forum [12]. The reasons for choosing Forum are:

- (1) the notion of formulas as resources peculiar of linear logic allows us to naturally encode several types of provability relations at the object level (e.g. two kind of sequents that depend on the *polarity* of goals as in Lifschitz [9]);
- (2) Forum provides an interpretation of linear logic formulas in terms of *programs* and *goals* that is close to the usual notions we find in logic programming languages. This interpretation of linear logic theories simplifies the encoding of the operational aspects related to SLDNF resolution.

Our encoding of Lifschitza calculus in Forum shares some similarities with previous works relating linear logic and negation as failure [2, 4, 3], and, in particular, with the work of Jeavons in [7]. Specifically, in our encoding we use the linear logic connectives with a semantic close to that used in [7]. However, our approach tries to fill the gap between the logic formalization in [7] of negation as failure, and the operational description of the approaches such as [13, 14, 9]. Forum is a logical tool that seems suitable to achieve this goal. In fact, Forum provability is given via an extension of the notion of uniform proofs [12] to multi-conclusion sequent calculi. Intuitively, uniform proofs correspond to cut-free, qoal-driven proofs, a notion at the basis of the operational interpretation of logic programming. The power of linear logic allows us to represent an SLDNF derivation by using a single Forum proof. In fact, the combination of multiplicative dijunction and additive disjunction allows us to naturally represent special constructors (like the one used in [11]) to keep track of alternating OR and AND branches (needed to check whether a derivation can finitely fail) within a single SLD derivation. As a consequence the linear logic completion presented in this paper turns out to be both a declarative (the Forum theory encoding the completion) and an operational description (the uniform proofs associated to a given general goal) of negation as failure, with a formal correspondance with the SLDNF calculus of Lifschitz.

Plan of the paper. In Section 2 we will introduce some preliminary notions (negation as failure, linear logic programming and Forum) needed in the sequel of the paper. In Section 3 we will introduce the Lifschitz calculus for negationa as failure. In Section 4 we will present the embedding of Lifschitz calculus into Forum, and we will study its properties. In Section 5 we will address some conclusions.

2 Preliminaries

2.1 General programs

A literal is an atom or its negation. A positive literal is an atom and a negative literal is a negated atom. A general goal is a finite conjunction of literals. The empty goal is denoted by \square . A general clause is an implication A:-G where G is a general goal. When the body is empty the clause is called a fact. A general program is a set of general clauses. A clause C defines a predicate p if $C = p(\bar{t})$:-G for some \bar{t} and some G. Hence, a program P defines a predicate p if a clause of P defines p. In the sequel we will use \bar{t} to denote vectors of terms t_1, \ldots, t_n , and p to denote

equality constraints between terms. The expression $\bar{x} = \bar{t}$ denotes the conjunction $x_1 = t_1 \wedge \ldots \wedge x_n = t_n$.

2.2 Negation as failure

Many efforts have been spent in order to formalize the operational meaning of SLDNF-resolution. SLDNF-resolution is an extension of SLD-resolution to general programs and goals, stating that $\neg A$ succeeds iff A finitely fails, and that $\neg A$ finitely fails iff A succeeds.

Differently from the case of SLD-derivation, where the search space is represented by a tree and a derivation by a path in the tree, in the case of SLDNF-resolution a derivation is a tree itself. Consider the program $P = \{A:-B, A:-C\}$ then, an SLD-derivation for $\neg A$ is given as follows:

$$\begin{array}{ccc} fail & fail \\ \uparrow & \uparrow \\ B & C & \square \\ \nwarrow \nearrow & \uparrow \\ A \longleftarrow \neg A \end{array}$$

In fact, it is necessary to inspect the SLDNF-tree for A to be able to answer to the query $\neg A$. Thus, SLDNF-derivations and SLDNF-trees interleave in the derivation of a general goal. In the sequel of the paper we will restrict ourselves to ground SLDNF-resolution. In particular, we will adopt *instantiation* instead of *unification* in resolution steps. The reason is that we will mainly focus on the relationships between SLDNF-derivations and Linear Logic proofs.

2.3 Linear Logic Programming

Forum [12] is a presentation of Linear Logic based on a uniform multi-conclusion sequent calculus. Forum represents a well-founded environment in which studying Linear Logic extensions of Logic programming. Following [6], in the sequel of the paper we will employ a higher-order logic programming language having the following features. Diffently from standard logic programming, in Forum it is possible to define programs consisting of multi-conclusion clauses of the form:

$$\forall (G_1 \& \dots \& G_k) \Rightarrow (A_1 \otimes \dots \otimes A_n \circ G)$$
or
$$\forall (G_1 \& \dots \& G_k) \Rightarrow (A_1 \otimes \dots \otimes A_n)$$

for $k \geq 0$ and n > 0, where A_i for $i:1,\ldots,n$ is an atomic formula, G_j for $j:1,\ldots k$ is a goal formula in which \Re , &, \forall , \top , $D \multimap G$ and $D \Rightarrow G$ may occur (D should have clausal form and G is, in turn, a goal formula). In the following, [D] denotes the set of instances of a formula D. Two zone-sequents are used to distinguish bewteen unbounded (i.e. program clauses) and bounded (clauses or goals) resources. Formally, a sequent has the form $P; \Gamma \longrightarrow \Delta$, where P is set of reusable program clauses, Γ is a multiset of clauses each one usable only once, and, finally, Δ is a

multiset of goals. A Forum derivation consists of a proof of a Forum sequent based on the goal-driven uniform proof system described in [12]. Intuitively, a Forum proof is built by first decomposing all goals in the right-hand side, then by applying clauses from P or from the bounded context in the left-hand side Δ , and so on, until an axiom is encountered. Goal formulas consisting of \mathfrak{A} , \mathfrak{A} , and \forall can be reduced deterministically to the corresponding subgoals. Specifically, proving $G_1 \,\mathfrak{A} \,G_2$, Δ reduces to proving G_1, G_2, Δ ; $G_1 \& G_2, \Delta$ reduces to the two subproofs G_1, Δ and G_2, Δ ; finally, $\forall x.G, \Delta$ reduces to the goal $G[d/x], \Delta$ with the proviso that d is a new constant not occurring in the current sequent. For the left rules, we will consider here proofs in which it is possible to focus on one single program clause, as specified by the following derived backchaining rule (an extension of SLD resolution to our clauses):

$$\frac{P; \longrightarrow G_1 \dots P; \longrightarrow G_k \quad P; \Gamma \longrightarrow G, \Delta}{P; \Gamma \longrightarrow^D \mathcal{A}, \Delta} \quad bc$$

where $(G_1 \& \dots \& G_k) \Rightarrow (A_1 \ \Re \dots \ \Re A_n \ \hookrightarrow \ G) \in [D]$, and $\mathcal{A} = \{A_1, \dots, A_n\}$. Note that G_1, \dots, G_k can be viewed as conditions under which the multiset rewriting rule rewrite A_1, \dots, A_n into G can be executed. The selection of the clause D on which we focus on is specified by the following rules:

$$\frac{D, P; \Gamma \longrightarrow^{D} \mathcal{A}}{D, P; \Gamma \longrightarrow \mathcal{A}} \quad decide_{1} \qquad \qquad \frac{P; \Gamma \longrightarrow^{D} \mathcal{A}}{P; \Gamma, D \longrightarrow \mathcal{A}} \quad decide_{2}$$

provided that A is a multiset of atomic formulas. Finally, note that, in case the selected rule has no body, we have the rule:

$$\frac{P; \longrightarrow G}{P; \longrightarrow^D A_1, \dots, A_n} bc$$

where $G \Rightarrow (A_1 \otimes ... \otimes A_n) \in [D]$. The last rule correspond to the application of a conditional fact.

3 The Lifschitz Calculus for Negation as Failure

Let \mathcal{P} be a set of predicate symbols, \mathcal{F} a set of function symbols. We will consider general programs as defined by the following grammar:

Clauses

$$C ::= A :- G \mid \forall C.$$

$$G ::= true \mid false \mid A \mid \neg G \mid G_1 \land G_2.$$

Programs

$$P ::= C, P \mid C.$$

Let \mathcal{L} be the resulting language. Given a program P, we aim at finding a proof of a goal G, in the following indicated by the sequent $\vdash G$, or of a goal $\neg G$, indicated by

Common Laws

$$\frac{\blacktriangleright \Delta}{\blacktriangleright true, \Delta} \quad red \qquad \frac{\blacktriangleright G_1, G_2, \Delta}{\blacktriangleright G_1 \land G_2, \Delta} \quad \wedge^{+/-}$$

Figure 1: The \mathcal{NAF} proof system

the sequent $\vdash G$. In order to formalize this notion of provability we will introduce a set of rules which generalize ground SLD-resolution with negation as failure. More precisely, we will consider sequents having the form $\vdash \Delta$ and $\vdash \Delta$, where Δ is a multiset of atomic formulas $p(\bar{t})$, or true. We will use $\triangleright \Delta$ to denote properties which apply both to $\vdash \Delta$ and $\vdash \Delta$. The proof system in Fig. 1 describes the operational meaning of the considered logic. By considering a goal $G_1 \wedge \ldots \wedge G_n$ as a multiset (see rule $\wedge^{+/-}$), it is possible to express a successful refutation of a positive goal as the simple axiom (ax^+) , namely all the subgoals have been reduced to the empty clause, by including the rule (red). The rule (bc^+) allows to compute ground resolvents of a given goal. The rule (bc^-) represents the counterpart of (ax^+) and (bc^+) . In fact, in case there are no clauses with head A the rule becomes the axiom for $\vdash A, \Delta$, i.e., the goal finitely fails selecting A. Otherwise, the goal finitely fails if all the possible ground resolvents finitely fail. The rule (\neg^+) tries to prove G finitely failed, in this case the result of the proof depends on Δ , whereas the rule (\neg^-) tries to find a refutation for G in order for the whole goal to fail. Here are some properties of the above proof system.

Proposition 3.1 The following properties hold:

- i) The sequents \vdash false, Δ and \vdash true are not provable in \mathbb{NAF} .
- ii) If the sequent $\vdash G$ is provable, then $\vdash G$ is not provable. The contrary does not hold.
- iii) If the sequent $\vdash G$ is provable, then $\vdash G$ is not provable. The contrary does not hold.
- iv) If the sequent $\vdash \neg G$ is provable, then $\vdash G$ is provable, and if the sequent $\vdash \neg G$ is provable, then $\vdash G$ is provable.

Proof 3.1 By an inspection of the proof system. The counter examples for the reverse implications (ii) and (iii) are given by the program p:-p and the sequents $\vdash \neg p$ and $\vdash p$, respectively.

3.1 A variation of the calculus

It is possible to further refine the previous calculus by including the connective \vee in the logic and assuming some restrictions on program definitions. Let us consider programs generated by the following grammar:

Clauses

$$\begin{array}{c} C ::= p(\bar{x}) := M \mid \forall C. \\ M ::= M_1 \vee M_2 \mid G. \\ G ::= true \mid false \mid A \mid \neg A \mid G_1 \wedge G_2. \end{array}$$

Programs

$$P ::= C, P \mid C.$$

Furthermore, consider now the class of programs obtained by P-formulas with the following restrictions:

- i) each predicate $q \in \mathcal{P}$ is defined by at most one clause of P.
- ii) for each predicate $q \in \mathcal{P}$ which is not defined in P we add a clause $\forall p(\bar{x})$:-false.
- $iii) \lor can only occur in clauses having the form$

$$\forall \bar{x}.p_0(\bar{x}):-p_1(\bar{x})\vee\ldots\vee p_k(\bar{x})$$

where p and p_i have the same arity, and $p_i \neq p_j$ for $i \neq j$.

Conditions i) and ii) imply that each predicate in \mathcal{P} is defined exactly by one clause. Condition iii) ensures that \vee is just used to re-introduce non-deterministic definitions of predicates as we will shown below. We will call the resulting language \mathcal{L}' . The aim of introducing \mathcal{L}' is to refine the proof system in Fig. 1, moving the universal quantification (for all clauses ...) in the side condition of rule bc from the meta level to the object level (there exists a 'completed' clause ...). Actually, we need a further refinement to represent failure of matching steps. Given a clause defining the predicate p, $p(\bar{t})$:-G let $c_{p(\bar{t})}[\bar{x}]$ be the formula $\exists \bar{y}$. $x_1 = t_1 \wedge \ldots x_n = t_n$, where \bar{y} are the variables in \bar{t} , \bar{x} are new variables. Let $\neg c_{p(\bar{t})}$ be the negation of $c_{p(\bar{t})}$. Furthermore, assume that $\models \neg c_{p(\bar{t})}[\bar{s}]$ iff $\bar{s} = \bar{t}$ is not solvable. According to the new assumptions we can reformulate the proof system of Fig. 1 as depicted in Fig. 2. It is clear now from the new rule (\vee^-) that allowing \vee to occur in the body of clauses mitigates the effects of restriction i). In fact, a program in \mathcal{L} can be encoded in \mathcal{L}' and viceversa. This can be achieved as follows. A predicate p defined by n C-clauses:

$$p(\bar{t_1})$$
:- $G_1,\ldots,p(\bar{t_n})$:- G_n

Laws for
$$\vdash$$

$$\frac{}{\vdash} ax^{+} \qquad \frac{\Vdash A \vdash \Delta}{\vdash \neg A, \Delta} \neg^{+} \qquad \frac{\vdash G_{i}, \Delta}{\vdash G_{1} \lor G_{2}, \Delta} \lor^{+} i \in \{1, 2\}$$

Laws for ⊢

$$\frac{}{\Vdash false,\Delta} \quad ax^{-} \qquad \frac{}{\Vdash p(\bar{s}),\Delta} \quad match \text{ if } \models \neg c_{p(\bar{t})}[\bar{s}] \qquad \frac{\vdash A}{\Vdash \neg A,\Delta} \quad \neg^{-}$$

$$\frac{\vdash G_{1},\Delta \quad \vdash G_{2},\Delta}{\vdash G_{1} \vee G_{2},\Delta} \quad \vee^{-}$$

Common Laws

Figure 2: The NAF proof system

can be defined by a C^{\vee} clause (and n auxiliary C-clauses) by splitting p into n subpredicates:

$$p(\bar{x}):-p_1(\bar{x}) \vee \ldots \vee p_n(\bar{x}), \ p_1(\bar{t_1}):-G_1, \ \ldots \ p_n(\bar{t_n}):-G_n.$$

The following proposition holds.

Proposition 3.2 Let P be an \mathcal{L} -program, G an \mathcal{L} -goal, and P', G' be their corresponding \mathcal{L}' images. Then, $\vdash G$ ($\vdash G$) is provable in the system of Fig. 1 if and only if $\vdash G'$ ($\vdash G'$) is provable in the system of Fig. 2.

Proof 3.2 The main point is to show the laws for \vdash are equivalent in the two systems. Intuitively, for each p there always exists one definition for p, and either the current goal $p(\bar{s})$ is not unifiable with the clause defining it, i.e. $\models \neg c_{p(\bar{t})}[\bar{s}]$, or the body of the definition is false, or, finally, the body is a goal G which must finitely fail, and then the rule bc must be applied.

4 Representing NAF in Linear Logic

The above introduced calculus can be encoded in a direct way in Linear Logic. The main points in the definition of the encoding are as follows:

• A derivation tree can be expressed in terms of a Forum proof by exploiting the sophisticate structure of Forum sequents and proofs. The encoding maps ∧ into ℜ ∨⁻ into &, and ∨⁺ into ⊕.

Encoding of programs: [P]

$$[C, P] = [C] \& [P].$$

Encoding of clauses:

Encoding of goals:

Figure 3: Encoding Programs in LL.

- The two types of sequents $\vdash A_1, \ldots, A_n$ and $\vdash A_1, \ldots, A_n$ can be represented by a LL sequent in which the atomic formulas \boxminus and \boxminus denote the polarity of the sequent. Precisely, the encoding is as follows: \mathcal{N}_{LL} ; $\longrightarrow \mathcal{A}_1 \ \Im \ldots \Im A_n \ \Im \boxminus$ and \mathcal{N}_{LL} ; $\longrightarrow \mathcal{A}_1 \ \Im \ldots \Im A_n \ \Im \boxminus$, where \mathcal{N}_{LL} will be introduced in the sequel.
- Switching the polarity of sequents from \boxplus to \boxminus and viceversa can be achieved by using a clause combining \backsim and \Rightarrow .

The two atomic formulas \boxplus and \boxminus denoting the polarity of sequents, must not be confused with the boolean constants true and false. The encoding of programs as in Section 3 is defined formally in Fig. 3. The LL theory that assigns a meaning to the non-logical constants true, false, = of Fig. 3 is given in Fig. 4. The encoding of \mathcal{NAF} -sequents into Forum sequents is defined in Fig. 4, too. Let us describe the intuition behind the encoding defined in Fig. 3. We first recall that in Section 3 we have considered a restricted class of the programs built using the connective \vee . Let $p(\bar{t})$:-G be a clause defining p. Furthermore, suppose that \vee does not occur in G. Then, $\llbracket \forall p(\bar{t})$:- $G \rrbracket$ is a &-conjunction (i.e. a Forum program) consisting of the following three clauses:

- $\forall (p(\bar{t}) ? \exists \Box) \circ [G]^- ? \exists \Box$.
- $\forall (p(\overline{t}) ? \exists \exists) \circ \llbracket G \rrbracket^+ ? \exists \exists$.
- $\forall \ \llbracket \neg c_{p(\bar{t})}[\bar{x}] \rrbracket \Rightarrow p(\bar{x}) \ \Im \Box \frown false \ \Im \Box.$

Since \vee does not occur in G, it follows that $\llbracket G \rrbracket^- = \llbracket G \rrbracket^+$. Thus, the previous program is equivalent to:

- $\forall p(\bar{t}) \hookrightarrow \llbracket G \rrbracket^+$.
- $\bullet \ \forall \ \llbracket \neg c_{p(\bar{t})}[\bar{x}] \rrbracket \ \Rightarrow \ (p(\bar{x}) \ \Im \boxminus) \circ -false.$

The former clause allows us to simulate the \mathcal{NAF} -rule bc. The latter one instead allows us to explicitly express failure due to non-matching between the selected atomic goal and the head of the considered clause, i.e., the condition $\llbracket \neg c_{p(\bar{t})}[\bar{x}] \rrbracket$ states that (the encoding of) the conjunction $x_1 = t_1 \wedge \ldots \wedge x_n = t_n$ should fail in order for the latter rule to be applied. (The Forum laws defining the predicate = are given in Fig. 4).

More in general, if \vee occurs in G, then \vee -subformulas are mapped to \oplus - or &-formulas depending on the *polarity* of the considered sequent.

Given a program P, let us denote with \mathcal{N}_{LL} the Forum theory $[\![P]\!]$, \mathcal{L}^+ , \mathcal{L}^- , $\mathcal{L}^=$ obtained by applying the encoding of Fig. 3 to P, and by enriching $[\![P]\!]$ with the laws of Fig. 4. Furthermore, given a multiset of M-formulas $\Delta = M_1, \ldots, M_n$, let $[\![\Delta]\!]$ be the multiset $[\![M_1]\!]$, ..., $[\![M_n]\!]$ for \blacksquare one of +, -. As shown in Fig. 5 and Fig. 6, the $\mathcal{N}\mathcal{A}\mathcal{F}$ -rules can be derived in Forum by exploiting the LL theory \mathcal{N}_{LL} . The counterpart of rule bc derives from the above mentioned property of the encoding of clauses without \vee in the body (they can be used both in negative and positive sequents). A particular attention must be paid to the encoding of the match rule that models the failure due to the non-matching of arguments passed to a predicate: for a sequent with negative polarity, it is always possible to apply the clause $[\![p(\bar{t}):-G]\!]^-$ to an atomic formula $p(\bar{s})$. In this case we have the following sequence of rules:

$$\begin{split} \mathcal{N}_{LL}; &\longrightarrow s_1 = t_1', \dots, s_n = t_n', \boxminus \\ & \vdots \quad \forall_r + \mathcal{R}_r \\ & \underbrace{\mathcal{N}_{LL}; \longrightarrow \llbracket \neg c_{p(\bar{s})}[\bar{t}] \rrbracket, \boxminus}_{\mathcal{N}_{LL}; \underbrace{\longrightarrow}_{false, \llbracket \Delta \rrbracket, \boxminus}_{bc}}_{\mathcal{N}_{LL}; \underbrace{\longrightarrow}_{false, \llbracket \Delta \rrbracket, \boxminus}_{bc}} \begin{array}{c} ax^- \\ bc \\ \\ & \underbrace{\mathcal{N}_{LL}; \underbrace{\longrightarrow}_{false, \llbracket \Delta \rrbracket, \boxminus}_{bc}}_{\mathcal{N}_{LL}; \underbrace{\longrightarrow}_{false, \llbracket \Delta \rrbracket, \boxminus}_{bc}} \end{array}$$

where t'_1 is obtained from t_1 by substituting each universally quantified variables with a newly introduced constant according to the right-introduction rule \forall_r of the universal quantifier in Forum. To complete the reconstruction of the *match* rule, we need the following lemma.

Lemma 4.1 Let \bar{s} be a tuple of ground terms and \bar{t} be a tuple of terms with free variables \bar{y} . Let \bar{d} be a tuple of new constants not occurring in $\mathcal{L}^=$ and let $\bar{t'} = \bar{t} \ [\bar{d}/\bar{y}]$. Then, $\mathcal{L}^=$; $\longrightarrow s_1 = t'_1 \ \Re \ldots \ \Re s_n = t'_n$, \boxminus is provable in Forum if and only if \bar{s} does not match \bar{t} .

Laws for
$$\vdash: \mathcal{L}^+$$
 \boxplus . (ax^+)
 $true \circ \vdash \bot$. (red)
 $(A \, \Im \, \boxminus) \Rightarrow (\neg A \, \Im \, \boxminus \, \circ \vdash \, \boxminus)$. (\neg^+)

Laws for $\Vdash: \mathcal{L}^ false \, \Im \, \boxminus \circ \vdash \top$. (ax^-)
 $(A \, \Im \, \boxminus) \Rightarrow (\neg A \, \Im \, \boxminus)$. (\neg^-)

Laws for equality : $\mathcal{L}^=$
 $(c = c) \circ \vdash true$, for each constant c .

 $\forall X_1 \dots X_n, Y_1, \dots, Y_k$.

 $(f(X_1, \dots, X_n) = g(Y_1, \dots, Y_k)) \circ \vdash false$. for $f \neq g$.

 $\forall X_1 \dots X_n, Y_1, \dots, Y_k$.

 $(f(X_1, \dots, X_n) = f(Y_1, \dots, Y_n)) \circ \vdash (X_1 = Y_1) \, \Im \dots \, \Im (X_n = Y_n)$.

 $\forall X, Y, C. \ (X = C) \, \Im (Y = C) \circ \vdash (X = C) \, \Im (Y = X)$.

Encoding of sequents : $\llbracket \blacktriangleright \Delta \rrbracket$
 $\llbracket \vdash \Delta \rrbracket = \llbracket P \rrbracket, \mathcal{L}^+, \mathcal{L}^-, \mathcal{L}^- \colon \longrightarrow \llbracket \Delta \rrbracket^+, \boxminus$.

Figure 4: The LL theory for NAF.

 $\llbracket \vdash \Delta \rrbracket = \llbracket P \rrbracket, \mathcal{L}^+, \mathcal{L}^-, \mathcal{L}^=; \longrightarrow \llbracket \Delta \rrbracket^-, \boxminus.$

Proof 4.1 (sketch) Let us consider the multiset $s_1 = t'_1, \ldots, s_n = t'_n$ Applying the rules of $\mathcal{L}^=$, each equation $s_i = t'_i$ can be reduced in a finite number of steps to a multiset c_1, \ldots, c_k s.t.: c_i is false or c_i is the atomic formula w = d where d is one of the constants in \bar{d} . At this point, we can apply the last laws of $\mathcal{L}^=$ which allows us to substitute w for d in all other equations having form v = d, yielding the equation v = w. Repeating this algorithm, we end up either in false (\bar{s} and \bar{t} do not match), in the empty multiset (i.e., they unify), or in the multiset $w_1 = d_1, \ldots, w_n = d_n$ with $d_i \neq d_j$, i.e., the sequent is not provable (we cannot prove that they do not unify).

The above lemma allows us to check whether the actual parameters match the arguments of a predicate by checking the provability of the encoding of $\neg c_{p(\bar{t})}[\bar{s}]$ against the theory $\mathcal{L}^=$ on a separate branch of a Forum proof. More precisely, we can state the following theorem.

Theorem 4.1 (Completeness of \mathcal{N}_{LL}) Let P be a program as in Section 3, Δ a multiset of goals. Then, $\blacktriangleright \Delta$ has a \mathcal{NAF} -proof iff $\llbracket \blacktriangleright \Delta \rrbracket$ has a Forum+ \mathcal{N}_{LL} -proof.

Proof 4.2 First we prove that if $\triangleright \Delta$ is provable then $\llbracket \triangleright \Delta \rrbracket$ is provable. The proof is by induction on the length of the proof of $\triangleright \Delta$. The basis of the induction has two subcases, namely (ax^+) and (ax^-) , which have a counterpart in \mathcal{N}_{LL} as shown in Fig. 5 and Fig. 6. The inductive step easily follows by applying, case by case,

$$\begin{array}{c}
N_{LL} \text{ rules} \\
\hline
\begin{array}{c}
\overline{N_{LL}; \stackrel{(ax^{+})}{\longrightarrow} \boxplus} & bc \\
\overline{N_{LL}; \stackrel{(ax^{+})}{\longrightarrow} \boxplus} & decide_{1} \\
\hline
\end{array}$$

$$\begin{array}{c}
\overline{N_{LL}; \stackrel{(ax^{+})}{\longrightarrow} \boxplus} & bc \\
\overline{N_{LL}; \stackrel{(ax^{+})}{\longrightarrow} \boxplus} & bc \\
\hline
\overline{N_{LL}; \stackrel{(red)}{\longrightarrow} true, \llbracket \Delta \rrbracket, \blacksquare} & bc \\
\overline{N_{LL}; \stackrel{(red)}{\longrightarrow} true, \llbracket \Delta \rrbracket, \blacksquare} & decide_{1} \\
\hline
\end{array}$$

$$\begin{array}{c}
\overline{N_{LL}; \stackrel{(red)}{\longrightarrow} true, \llbracket \Delta \rrbracket, \blacksquare} & decide_{1} \\
\hline
\end{array}$$

$$\begin{array}{c}
\overline{N_{LL}; \stackrel{(red)}{\longrightarrow} \llbracket G_{i} \rrbracket, \llbracket \Delta \rrbracket, \boxplus} & \oplus_{r} & i \in \{1, 2\} \\
\hline
\end{array}$$

$$\begin{array}{c}
\overline{N_{LL}; \stackrel{(red)}{\longrightarrow} \llbracket G_{1} \rrbracket, \llbracket \Delta \rrbracket, \boxplus} & \oplus_{r} & i \in \{1, 2\} \\
\hline
\end{array}$$

$$\begin{array}{c}
\overline{N_{LL}; \stackrel{(-+)}{\longrightarrow} A, \boxminus} & \overline{N_{LL}; \stackrel{(-+)}{\longrightarrow} A, \llbracket \Delta \rrbracket, \boxplus} & decide_{1} \\
\hline
\overline{N_{LL}; \stackrel{(-+)}{\longrightarrow} \neg A, \llbracket \Delta \rrbracket, \boxplus} & decide_{1} \\
\hline
\end{array}$$

$$\begin{array}{c}
\overline{N_{LL}; \stackrel{(-+)}{\longrightarrow} \neg A, \llbracket \Delta \rrbracket, \boxplus} & decide_{1} \\
\hline
\end{array}$$

Figure 5: Deriving the \mathcal{NAF} rules in Forum+ $\mathcal{N}_{LL}(1)$.

the inductive hypothesis to the premises of the schemes in Fig. 5. and in Fig. 6. Let us prove the other implication. The proof is now by induction on the length of the Forum-proof for $\llbracket \blacktriangleright \Delta \rrbracket = \mathcal{N}_{LL} \longrightarrow \llbracket \Delta \rrbracket^{\blacksquare}$, \blacksquare . First notice that $\llbracket \Delta \rrbracket$ is a multiset of formulas in which only the connectives \oplus , &, \Im , \top and the non-logical symbols $p \in \mathcal{P}$, true, false, \neg , =, can occur. Thus, in a Forum-proof for $\llbracket \blacktriangleright \Delta \rrbracket$ only the rightrules \oplus_r , $\&_r$, \Im_r , \top_r can occur. Furthermore, the only left-rules applicable are bc (over formulas in \mathcal{N}_{LL}) and $(decide_1)$. To prove the base case we must consider two subcases, one of length one, namely the counterpart of the rule (ax^+) , one of length two, namely the counterpart of rule (ax^-) , since there are no formulas s.t. $\llbracket F \rrbracket = \top$. In the first case $\llbracket \Delta \rrbracket$ must be equal to $\mathcal{N}_{LL} \longrightarrow \boxplus$, since the side condition of the Forum bc rule requires the right hand side to match the fact $\boxplus \in \mathcal{N}_{LL}$ to be correctly applied. Thus, $\Delta = \emptyset$ and \vdash is provable. In the second case, Δ contains at least false, since by hypothesis the proof results by a bc step over the rule $false \Im \boxplus -\top$. Thus, $\Vdash false$, Δ is provable by (ax^-) . The inductive step is by cases on the last

rule. If the last rule is a right-introduction rule, then it must be one of \bigoplus_r , $\&_r$, \Re_r . For instance, if the last rule is \bigoplus_r , then, by definition, $\llbracket \blacktriangleright \Delta \rrbracket = \llbracket \vdash G_1 \lor G_2, \Gamma \rrbracket$, i.e., \aleph_{LL} ; $\longrightarrow \llbracket G_1 \rrbracket^+ \oplus \llbracket G_2 \rrbracket^+, \llbracket \Gamma \rrbracket^+, \boxplus$. The thesis now follows by applying the inductive hypothesis to the premises of the counterpart of (\vee^+) in Fig. 5, which ensures the existence of a proof for $\vdash G_i$, Γ for $i \in \{1,2\}$ and thus a proof for $\vdash G_1 \lor G_2, \Gamma$.

Finally, if the last rule is a bc over a clause in \mathcal{N}_{LL} , we first notice that it must be one of the scheme in Fig. 6. Now observe that in each scheme once a rule has been selected, i.e., a $decide_1$ has been applied, the sequence of rule is determined as far as the premises are introduced. For instance, let us consider the more complex one, i.e., an application of (\neg^+) , when the flag is set to \square . By construction, $\triangleright \Delta$ must be equal to $\lnot \neg A$, $\lnot \square$, i.e., \mathcal{N}_{LL} ; $\longrightarrow \neg A$, $\lnot \square$ Now after the application of $decide_1$ over the rule (\neg^+) we are forced, by the focusing property of Forum, to apply a bc step. This yields two premises, namely \mathcal{N}_{LL} ; $\longrightarrow A \cong \square$ and \mathcal{N}_{LL} ; $\longrightarrow \llbracket \Gamma \rrbracket^+, \square$. Now, by the uniformity of Forum proofs, we are forced to apply the right-rules to the left premise obtaining \mathcal{N}_{LL} ; $\longrightarrow A$, \square and \square and \square \square \square \square \square \square \square \square These, in turn, correspond, by definition, to \square \square and \square \square respectively. Thus, we can apply the inductive hypothesis, and the $\mathcal{N}A\mathcal{F}$ -rule (\neg^+) to obtain the thesis.

The other cases can be proved in a similar way.

The relationships between the two calculi become more evident if we collapse the Forum-schemes of Fig. 5 and Fig. 6 as shown in Fig. 7. Here P is the program which results by collapsing clauses with complex body (i.e., containing & and \oplus) and clauses with simple goals (i.e., whose goals contains at most the connective \Re), similarly to the step performed in the Horn-Clause example.

5 Conclusions

Differently from previous works on negation as failure in linear logic, we have given here a linear logic completion which has the following operational properties.

- The completion can be represented as a theory in Forum [12];
- an SLDNF derivation is represented via a Forum proof, that enjoys the property of being uniform (goal-driven);
- thanks to the interpretation of Forum proofs as computations it comes natural to give an operational interpretation of a general goal G w.r.t. a program P, by using the corresponding Forum proof of its encoding $[\![G]\!]$ w.r.t. $[\![P]\!]$.

The approaches in [2, 4, 3] successively revised by Jeavons in [7] are based on a different representation of goal and clauses. Goals are tensor of literals and the negation is the involutive negation of linear logic. Our encoding follows instead the methodology suggested in [6], in order to exploit multiplicative disjunction to represent a multiset of resources, & to create proofs with several independent branches.

As future work, it would be interesting to investigate the applicability of more general proof calculi like the *Calculus of Structures* of [8] as possible reference logic for negation as failure.

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 \mathcal{N}_{LL} rules

$$(ax^{-}) \qquad \frac{\overline{N_{LL}; \longrightarrow \top, \llbracket \Delta \rrbracket, \boxminus}}{N_{LL}; \stackrel{(ax^{-})}{\longrightarrow} false, \llbracket \Delta \rrbracket, \boxminus} \qquad bc} \\ \overline{N_{LL}; \stackrel{(ax^{-})}{\longrightarrow} false, \llbracket \Delta \rrbracket, \boxminus}} \qquad bc} \\ \overline{N_{LL}; \longrightarrow false, \llbracket \Delta \rrbracket, \boxminus} \qquad decide_{1}} \\ (V^{-}) \qquad \overline{N_{LL}; \longrightarrow \llbracket G_{1} \rrbracket, \llbracket \Delta \rrbracket, \boxminus} \qquad N_{LL}; \longrightarrow \llbracket G_{2} \rrbracket, \llbracket \Delta \rrbracket, \boxminus}} \qquad \&_{r} \\ \\ \overline{N_{LL}; \longrightarrow \llbracket G_{1} \rrbracket, \llbracket G_{2} \rrbracket, \llbracket \Delta \rrbracket, \boxminus}} \qquad bc} \\ \overline{N_{LL}; \longrightarrow \neg A, \llbracket \Delta \rrbracket, \boxminus}} \qquad bc} \\ \overline{N_{LL}; \longrightarrow \neg A, \llbracket \Delta \rrbracket, \boxminus}} \qquad decide_{1}} \\ (\wedge^{+/-}) \qquad \overline{N_{LL}; \longrightarrow \llbracket G_{1} \rrbracket, \llbracket G_{2} \rrbracket, \llbracket \Delta \rrbracket, \blacksquare}} \qquad \&_{r} \\ \overline{N_{LL}; \longrightarrow \llbracket M \rrbracket^{\blacksquare}, \llbracket \Delta \rrbracket, \blacksquare}} \qquad \&_{r} \\ \hline \underline{N_{LL}; \longrightarrow \llbracket M \rrbracket^{\blacksquare}, \llbracket \Delta \rrbracket, \blacksquare}} \qquad bc} \\ \overline{N_{LL}; \longrightarrow \llbracket M \rrbracket^{\blacksquare}, \llbracket \Delta \rrbracket, \blacksquare}} \qquad bc} \\ \overline{N_{LL}; \longrightarrow \llbracket M \rrbracket^{\blacksquare}, \llbracket \Delta \rrbracket, \blacksquare}} \qquad decide_{1} \\ \hline N_{LL}; \longrightarrow \llbracket M \rrbracket^{\blacksquare}, \llbracket \Delta \rrbracket, \blacksquare} \qquad decide_{1} \\ \hline N_{LL}; \longrightarrow \llbracket M \rrbracket^{\blacksquare}, \llbracket \Delta \rrbracket, \blacksquare} \qquad decide_{1} \\ \hline N_{LL}; \longrightarrow \llbracket M \rrbracket^{\blacksquare}, \llbracket \Delta \rrbracket, \blacksquare} \qquad decide_{1} \\ \hline N_{LL}; \longrightarrow \llbracket M \rrbracket^{\blacksquare}, \llbracket \Delta \rrbracket, \blacksquare} \qquad decide_{1} \\ \hline N_{LL}; \longrightarrow \llbracket M \rrbracket, \llbracket \Delta \rrbracket, \blacksquare} \qquad decide_{1} \\ \hline N_{LL}; \longrightarrow \llbracket M \rrbracket, \llbracket \Delta \rrbracket, \blacksquare} \qquad decide_{1} \\ \hline N_{LL}; \longrightarrow \llbracket M \rrbracket, \llbracket \Delta \rrbracket, \blacksquare} \qquad decide_{1} \\ \hline N_{LL}; \longrightarrow \llbracket M \rrbracket, \llbracket \Delta \rrbracket, \blacksquare} \qquad decide_{1} \\ \hline N_{LL}; \longrightarrow \llbracket M \rrbracket, \llbracket \Delta \rrbracket, \blacksquare} \qquad decide_{1} \\ \hline N_{LL}; \longrightarrow \llbracket M \rrbracket, \llbracket \Delta \rrbracket, \blacksquare} \qquad decide_{1} \\ \hline N_{LL}; \longrightarrow \llbracket M \rrbracket, \llbracket \Delta \rrbracket, \blacksquare} \qquad decide_{1} \\ \hline N_{LL}; \longrightarrow \llbracket M \rrbracket, \llbracket \Delta \rrbracket, \blacksquare} \qquad decide_{1} \\ \hline N_{LL}; \longrightarrow \llbracket M \rrbracket, \llbracket \Delta \rrbracket, \blacksquare} \qquad decide_{1} \\ \hline N_{LL}; \longrightarrow \llbracket M \rrbracket, \llbracket \Delta \rrbracket, \blacksquare} \qquad decide_{1} \\ \hline N_{LL}; \longrightarrow \llbracket M \rrbracket, \llbracket \Delta \rrbracket, \blacksquare} \qquad decide_{1} \\ \hline N_{LL}; \longrightarrow \llbracket M \rrbracket, \llbracket \Delta \rrbracket, \blacksquare} \qquad decide_{1} \\ \hline N_{LL}; \longrightarrow \llbracket M \rrbracket, \llbracket \Delta \rrbracket, \blacksquare} \qquad decide_{1} \\ \hline N_{LL}; \longrightarrow \llbracket M \rrbracket, \llbracket \Delta \rrbracket, \blacksquare} \qquad decide_{1} \\ \hline N_{LL}; \longrightarrow \llbracket M \rrbracket, \llbracket \Delta \rrbracket, \blacksquare} \qquad decide_{1} \\ \hline N_{LL}; \longrightarrow \llbracket M \rrbracket, \llbracket \Delta \rrbracket, \blacksquare} \qquad decide_{1} \\ \hline N_{LL}; \longrightarrow \llbracket M \rrbracket, \llbracket \Delta \rrbracket, \blacksquare} \qquad decide_{1}$$

Figure 6: Deriving the \mathcal{NAF} rules in Forum+ $\mathcal{N}_{LL}(2)$.

Positive Polarity

Negative Polarity

$$\frac{}{\mathcal{N}_{LL}; \longrightarrow false, \Delta, \boxminus} \quad ax^{-} \qquad \frac{\mathcal{N}_{LL}; \longrightarrow A, \boxminus}{\mathcal{N}_{LL}; \longrightarrow \neg A, \Delta, \boxminus} \quad \neg^{-}$$

$$\frac{\mathcal{N}_{LL}; \longrightarrow G_1, \Delta, \boxminus \dots \mathcal{N}_{LL}; \longrightarrow G_n, \Delta, \boxminus}{\mathcal{N}_{LL}; \longrightarrow A, \Delta, \boxminus} bc^-$$

where $A := G_1, \ldots, A := G_n$ are all the clauses in [P] with head A.

Neutral Polarity

$$\frac{\mathcal{N}_{LL}; \longrightarrow G_1, G_2, \Delta, \blacksquare}{\mathcal{N}_{LL}; \longrightarrow G_1 \ \Re G_2, \Delta, \blacksquare} \quad \wedge^{+/-} \qquad \frac{\mathcal{N}_{LL}; \longrightarrow \Delta, \blacksquare}{\mathcal{N}_{LL}; \longrightarrow true, \Delta, \blacksquare} \quad red$$

Figure 7: The proof system \mathcal{N}_{LL} .